

Outline:

- More substitutions
- Exact differentials
- Integrating Factors

Last Time:

We defined a **separable first-order ODE**

$$\dot{x}(t) = g(t)f(x) \quad (\text{or, alternately } g(t)dt + f(x)dx = 0)$$

We can solve these by integrating $\int g(t)dt + \int f(x)dx = 0$.

We also defined **homogeneous functions** $f(tx, ty) = t^n f(x, y)$

And showed that an ODE $P(x, y)dx + Q(x, y)dy = 0$,

with **homogeneous coefficients** $P(x, y)$ and $Q(x, y)$ of the same order, can be solved by substituting

$$y = ux, \quad dy = udx + xdu$$

which turns it into a separable ODE.

Linear Coefficients

We label ODEs of the form $(a_1x + b_1y + c_1)dx + (a_2x + b_2y + c_2)dy = 0$ as having **linear coefficients**

We call these linear because

$$a_1x + b_1y + c_1 = 0$$

$$a_2x + b_2y + c_2 = 0$$

define lines in the XY -plane.

What do we know how to solve?

1. separable equations

2. homogeneous coefficients

↑ transform

We want to transform **linear coefficients** into \uparrow

Let's start with an easy example. Suppose $c_1 = c_2 = 0$

$$(a_1x + b_1y)dx + (a_2x + b_2y)dy = 0$$

Then $(a_1x + b_1y)$, $(a_2x + b_2y)$ are already homogeneous

$$\text{Let } y = ux \quad dy = udx + xdu$$

$$\Rightarrow (a_1x + b_1ux)dx + (a_2x + b_2ux)(udx + xdu) = 0$$

$$\Rightarrow [a_1x + b_1ux + a_2ux + b_2u^2x]dx + [a_2x^2 + b_2ux^2]du = 0$$

$$\Rightarrow x(a_1 + b_1u + a_2u + b_2u^2)dx + x^2(a_2 + b_2u)du = 0$$

If $x \neq 0$, and $a_1 + b_1u + a_2u + b_2u^2 \neq 0$,

$$\frac{1}{x}dx + \frac{a_2 + b_2u}{a_1 + b_1u + a_2u + b_2u^2}du = 0 \quad \leftarrow \text{separable}$$

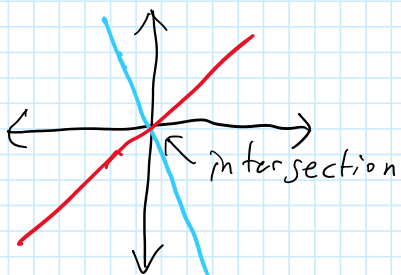
Note that you also have to check if $x = 0$
 $a_1 + b_1u + a_2u + b_2u^2 = 0$
 are solutions

What was the key? Linear coefficients without constants are homogeneous.

Let's look at \mathbb{R}^2 geometry of an example.

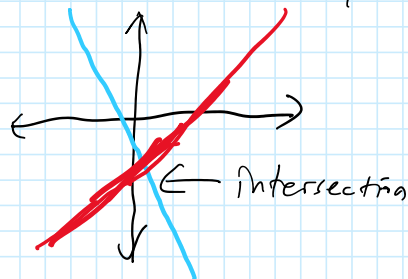
$$(2x + y)dx + (x - y)dy = 0$$

$$\begin{cases} 2x + y = 0 \\ x - y = 0 \end{cases} \Rightarrow \begin{cases} y = -2x \\ y = x \end{cases}$$



$$(2x + y + 1)dx + (x - y - 4)dy = 0$$

$$\begin{cases} 2x + y + 1 = 0 \\ x - y - 4 = 0 \end{cases} \Rightarrow \begin{cases} y = -2x - 1 \\ y = x - 4 \end{cases}$$



Having a constant term means that the lines intersect at ^{not} the origin.

Can we change the coordinate system so these lines intersect at the origin?

Method 1: Find the intersection pt and translate it

$$\left. \begin{array}{l} y = 2x - 1 \\ y = x - 4 \end{array} \right\} \Rightarrow \begin{array}{l} -2x - 1 = x - 4 \\ 3x = 3 \\ x = 1 \\ y = -3 \end{array} \quad \begin{array}{l} \text{let } x = \bar{x} + 1 \\ y = \bar{y} - 3 \end{array} \quad \begin{array}{l} dx = d\bar{x} \\ dy = d\bar{y} \end{array}$$

$$(2x + y + 1) dx + (x - y - 4) dy = 0$$

$$(2\bar{x} + 2 + \bar{y} - 3 + 1) d\bar{x} + (\bar{x} + 1 - \bar{y} + 3 - 4) d\bar{y} = 0$$

homogeneous $\rightarrow (2\bar{x} + \bar{y}) d\bar{x} + (\bar{x} - \bar{y}) d\bar{y} = 0$

Method 2: Use the two lines as the new coordinate system

$$\left. \begin{array}{l} \text{let } u = 2x + y + 1 \\ v = x - y - 4 \end{array} \right\} \begin{array}{l} du = 2dx + dy \\ dv = dx - dy \end{array} \quad \begin{array}{l} du + dv = 3dx \\ dx = \frac{du + dv}{3} \end{array} \quad \begin{array}{l} dy = \frac{du - 2dv}{3} \end{array}$$

$$u \left(\frac{du + dv}{3} \right) + v \left(\frac{du - 2dv}{3} \right) = 0$$

$$u(du + dv) + v(du - 2dv) = 0$$

$$(u + v) du + (u - 2v) dv = 0 \leftarrow \text{homogeneous}$$

This only works when the lines intersect

Method 3: If the lines don't intersect, we only need one substitution

$$(x + 2y + 5) dx + (2x + 4y - 3) dy = 0$$

$$x + 2y + 5 = 0$$

$$2x + 4y - 3 = 0$$

$$2y = -x - 5$$

$$4y = -2x + 3$$

$$y = -\frac{x}{2} - \frac{5}{2}$$

$$y = -\frac{x}{2} + \frac{3}{4}$$



What if we choose one line as a new variable and keep an old variable,

$$\text{let } u = x + 2y + 5 \quad du = dx + 2dy$$

$$x = u - 2y - 5 \quad dx = du - 2dy$$

$$u(du - 2dy) + (2u - 13) dy = 0 \leftarrow \text{separable}$$

$$u du - 13 dy = 0$$

Exact Differentials

From multivariable calculus (the coreq B 41), we can define the total differential of a function $z = f(x, y)$ by

$$dz = \frac{\partial f(x, y)}{\partial x} dx + \frac{\partial f(x, y)}{\partial y} dy.$$

Ex $z = x^2 + y^2$

$$dz = 2x dx + 2y dy$$

Def. A differential expression

$$P(x, y) dx + Q(x, y) dy$$

is called an **exact differential** if it is the total differential of some function $f(x, y)$.

i.e. if $P(x, y) = \frac{\partial}{\partial x} f(x, y)$ and $Q(x, y) = \frac{\partial}{\partial y} f(x, y)$.

When an exact differential appears in an ODE, and if we know the function it is the total differential of, then we can easily integrate the **exact differential equation** to get a 1-parameter family of solutions

$$f(x, y) = c.$$

Ex. $(6xy + 5y) dx + (3x^2 + 5x + 3y^2) dy = 0$

$$f(x, y) = 3x^2 y + 5xy + y^3$$

Then $3x^2 y + 5xy + y^3 = c$ is a solution.

How do we recognize exact differentials?

Theorem 9.3

Tenenbaum

$P(x, y) dx + Q(x, y) dy = 0$ is exact if and only if

$$\frac{\partial P(x, y)}{\partial y} = \frac{\partial Q(x, y)}{\partial x},$$

where $\frac{\partial P}{\partial x}$, $\frac{\partial P}{\partial y}$, $\frac{\partial Q}{\partial x}$, $\frac{\partial Q}{\partial y}$ all exist and are continuous in c simply

where $\frac{\partial r}{\partial x}$, $\frac{\partial r}{\partial y}$, $\frac{\partial Q}{\partial x}$, $\frac{\partial Q}{\partial y}$ all exist and are continuous in a simply connected region $R \subseteq \mathbb{R}^2$.

Ex. $2x dx + 3y dy = 0$